

Haptic Rendering For Simulation Of Fine Manipulation By Dangxiao Wang;Jing Xiao;Yuru Zhang

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Jing Xiao

Interests: Artificial Intelligence, Machine Learning & Pattern Recognition, freedom haptic rendering for fine manipulation Wang, Xin Zhang, Yuru Zhang, Jing Xiao.

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Haptic Rendering Beyond Visual Computing Haptics in Minimally Invasive Surgical Simulation

3D Real-Time GPU Smoke Simulation with Haptic

May 03, 2008 Physically-Based Real-Time GPU 3D Smoke Simulation with Haptic Rendering. 1. Based on Navier-Stoke equation for fluid simulation. 2. Numerical methods

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Interactive simulation of a deformable hand for

Operations such as object manipulation and palpation rely on the fine perception of contact forces, both in time and space. Haptic simulation of grasping, with the

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Using analytical force model for efficient deformation simulation and haptic rendering of soft objects
Xue-Jian He, Kup-Sze Choi show all 2 hide

TDGS - "Yuru Zhang"

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Interactive haptic deformation of dynamic soft

Six-degree-of-freedom haptic rendering using incremental and localized computations, Wang Jing, Yuru Zhang: Pages: 409 - 412: doi>10.1145

Bone drilling simulation based on six

Bone drilling simulation based on six degree-of-freedom haptic rendering XJ. He¹ The University of Hong Kong ABSTRACT YH. Chen² The University of Hong Kong Bone

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Haptic Rendering for Laparoscopic Surgery Simulation & Related Studies:
10.4018/978-1-59904-889-5.ch081: This project concerns the application of haptic feedback to a

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Stimulation current control for load-aware

1. Introduction. The research in haptic rendering has made a significant contribution in disciplines ranging from robotics, computational geometry, and computer

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Feng,Jing;Wang,Zhi-Qiang;Yan,Jun;Zhang,Mi-Lin Zhang,Guang-Pu;Yin,Jing-Wei;Wang,Xiao-Lin Zhang,Aiguo Numerical simulation research of NO_x emissions

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Six Degree-of Freedom Haptic Rendering for Dental Implantology Simulation the jawbone erosion during drilling which is relevant for 6DoF haptic rendering.

Haptic Rendering for Simulation of Fine

Haptic Rendering for Simulation of Fine Manipulation. Dangxiao Wang, Jing Xiao, Yuru Zhang. Springer-Verlag, 2014: hbk

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